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# Bilinear Control Processes With Applications to Engineering, Ecology, and Medicine

Ronald R. Mohler



# Bilinear Control Processes With Applications To Engineering Ecology And Medicine

**LM Reder**



## **Bilinear Control Processes With Applications To Engineering Ecology And Medicine:**

**Bilinear Control Processes: with Applications to Engineering, Ecology, and Medicine** Mohler, 1974-03-11 Bilinear Control Processes with Applications to Engineering Ecology and Medicine *Bilinear control processes : with applications to engineering, ecology, and medicine* Ronald R. Mohler, 1973 Recent Advances in Modeling, Analysis and Systems Control: Theoretical Aspects and Applications El Hassan Zerrik, Said Melliani, Oscar Castillo, 2019-08-26 This book describes recent developments in a wide range of areas including the modeling analysis and control of dynamical systems and explores related applications The book provided a forum where researchers have shared their ideas results on theory and experiments in application problems The current literature devoted to dynamical systems is quite large and the authors choice for the considered topics was motivated by the following considerations Firstly the mathematical jargon for systems theory remains quite complex and the authors feel strongly that they have to maintain connections between the people of this research field Secondly dynamical systems cover a wider range of applications including engineering life sciences and environment The authors consider that the book is an important contribution to the state of the art in the fuzzy and dynamical systems areas

Bifurcation Theory with Applications Terry E. Moschandreou, 2024-12-11 Bifurcation Theory with Applications is a collection of chapters that describe the theory and application of nonlinear dynamics to a wide variety of problems in physics and engineering Each chapter is self contained and includes an introduction main contributions and details of up to date theoretical computational and experimental results The book examines various practical systems including models of target detection in cells through the analysis of bio nanomachine attractant and repellent concentrations It addresses the quasistatic evolution of anelastic structures explores the generation of triangular patterns through anisotropic diffusion and discusses the stabilization of time delay distributed bilinear systems in spatial domains Topics also include optimal control challenges in bilinear systems with unbounded and bounded control sets forward bifurcation in hepatitis B virus infection models and the bifurcation of hematological stem cells with feedback control in a biological context The book is designed for theorists applied mathematicians and engineers across diverse scientific disciplines serving as a valuable resource for anyone interested in bifurcation theory s wide ranging applications Recent Advances in Intuitionistic Fuzzy Logic Systems and Mathematics Said Melliani, Oscar Castillo, 2020-10-12 This book provides an overview of the state of the art in both the theory and methods of intuitionistic fuzzy logic partial differential equations and numerical methods in informatics Covering topics such as fuzzy intuitionistic Hilbert spaces intuitionistic fuzzy differential equations fuzzy intuitionistic metric spaces and numerical methods for differential equations it discusses applications such as fuzzy real time scheduling intelligent control diagnostics and time series prediction The book features selected contributions presented at the 6th international congress of the Moroccan Applied Mathematics Society which took place at Sultan Moulay Slimane University Beni Mellal Morocco from 7 to 9 November 2019 *PEM Fuel Cells with Bio-Ethanol Processor Systems* Marta S.

Basualdo, Diego Feroldi, Rachid Outbib, 2011-10-30 An apparently appropriate control scheme for PEM fuel cells may actually lead to an inoperable plant when it is connected to other unit operations in a process with recycle streams and energy integration PEM Fuel Cells with Bio Ethanol Processor Systems presents a control system design that provides basic regulation of the hydrogen production process with PEM fuel cells It then goes on to construct a fault diagnosis system to improve plant safety above this control structure PEM Fuel Cells with Bio Ethanol Processor Systems is divided into two parts the first covers fuel cells and the second discusses plants for hydrogen production from bio ethanol to feed PEM fuel cells Both parts give detailed analyses of modeling simulation advanced control and fault diagnosis They give an extensive in depth discussion of the problems that can occur in fuel cell systems and propose a way to control these systems through advanced control algorithms A significant part of the book is also given over to computer aided engineering software tools that can be used to evaluate the dynamic performance of the overall plant PEM Fuel Cells with Bio Ethanol Processor Systems is intended for use by researchers and advanced students on chemical electrical electronic and mechanical engineering courses in which dynamics and control are incorporated with the traditional steady state coverage of flowsheet synthesis engineering economics and optimization

**Neural Adaptive Control Technology** Rafa? ?bikowski, Kenneth J. Hunt, 1996 This book is an outgrowth of the workshop on Neural Adaptive Control Technology NACT I held in 1995 in Glasgow Selected workshop participants were asked to substantially expand and revise their contributions to make them into full papers The workshop was organised in connection with a three year European Union funded Basic Research Project in the ESPRIT framework called NACT a collaboration between Daimler Benz Germany and the University of Glasgow Scotland A major aim of the NACT project is to develop a systematic engineering procedure for designing neural controllers for nonlinear dynamic systems The techniques developed are being evaluated on concrete industrial problems from Daimler Benz In the book emphasis is put on development of sound theory of neural adaptive control for nonlinear control systems but firmly anchored in the engineering context of industrial practice Therefore the contributors are both renowned academics and practitioners from major industrial users of neurocontrol

*Geometric Methods in System Theory* D.Q. Mayne, R.W. Brockett, 2012-12-06 Geometric Methods in System Theory In automatic control there are a large number of applications of a fairly simple type for which the motion of the state variables is not free to evolve in a vector space but rather must satisfy some constraints Examples are numerous in a switched lossless electrical network energy is conserved and the state evolves on an ellipsoid surface defined by  $x^T Q x$  equals a constant in the control of finite state continuous time Markov processes the state evolves on the set  $x \in \mathbb{R}^n$   $x_1 \geq 0$  The control of rigid body motions and trajectory control leads to problems of this type There has been under way now for some time an effort to build up enough control theory to enable one to treat these problems in a more or less routine way It is important to emphasise that the ordinary vector space linear theory often gives the wrong insight and thus should not be relied upon

*Intelligent Industrial Systems: Modeling,*

*Automation and Adaptive Behavior* Rigatos, Gerasimos, 2010-06-30 In recent years there has been growing interest in industrial systems especially in robotic manipulators and mobile robot systems As the cost of robots goes down and become more compact the number of industrial applications of robotic systems increases Moreover there is need to design industrial systems with intelligence autonomous decision making capabilities and self diagnosing properties Intelligent Industrial Systems Modeling Automation and Adaptive Behavior analyzes current trends in industrial systems design such as intelligent industrial and mobile robotics complex electromechanical systems fault diagnosis and avoidance of critical conditions optimization and adaptive behavior This book discusses examples from major areas of research for engineers and researchers providing an extensive background on robotics and industrial systems with intelligence autonomy and adaptive behavior giving emphasis to industrial systems design

**Realization and Modelling in System Theory** A.C. Ran, J.H. van Schuppen, Marinus Kaashoek, 2013-03-07 This volume is the first of the three volume publication containing the proceedings of the 1989 International Symposium on the Mathematical Theory of Networks and Systems MTNS 89 which was held in Amsterdam The Netherlands June 19 23 1989 The International Symposia MTNS focus attention on problems from system and control theory circuit theory and signal processing which in general require application of sophisticated mathematical tools such as from function and operator theory linear algebra and matrix theory differential and algebraic geometry The interaction between advanced mathematical methods and practical engineering problems of circuits systems and control which is typical for MTNS turns out to be most effective and is as these proceedings show a continuing source of exciting advances The first volume contains invited papers and a large selection of other symposium presentations on the general theory of deterministic and stochastic systems with an emphasis on realization and modelling A wide variety of recent results on approximate realization and system identification stochastic dynamical systems discrete event systems o systems singular systems and nonstandard models IS presented Preface vi Also a few papers on applications in hydrology and hydraulics are included The titles of the two other volumes are Robust Control of Linear Sys tems and Nonlinear Control volume 2 and Signal Processing Scatter ing and Operator Theory and Numerical Methods volume 3 The Editors are most grateful to the about 300 reviewers for their help in the refereeing process The Editors thank Ms G Bijleveld and Ms

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