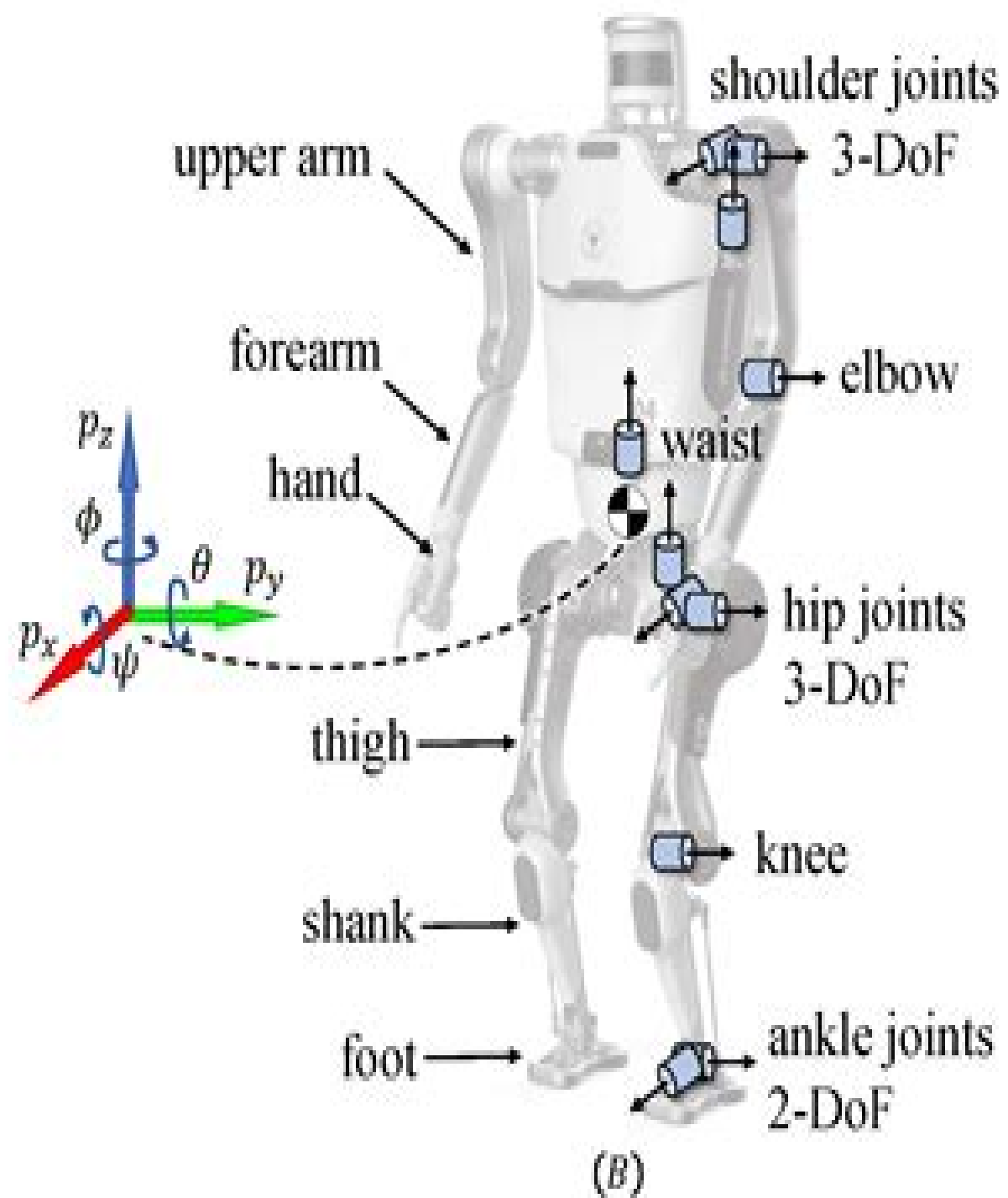




Biped Locomotion

Ensheng Dong



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Feedback Control of Dynamic Bipedal Robot Locomotion Eric R. Westervelt, Jessy W. Grizzle, Christine Chevallereau, Jun Ho Choi, Benjamin Morris, 2018-10-03 Bipedal locomotion is among the most difficult challenges in control engineering Most books treat the subject from a quasi static perspective overlooking the hybrid nature of bipedal mechanics Feedback Control of Dynamic Bipedal Robot Locomotion is the first book to present a comprehensive and mathematically sound treatment of feedback design for achieving stable agile and efficient locomotion in bipedal robots In this unique and groundbreaking treatise expert authors lead you systematically through every step of the process including Mathematical modeling of walking and running gaits in planar robots Analysis of periodic orbits in hybrid systems Design and analysis of feedback systems for achieving stable periodic motions Algorithms for synthesizing feedback controllers Detailed simulation examples Experimental implementations on two bipedal test beds The elegance of the authors approach is evident in the marriage of control theory and mechanics uniting control based presentation and mathematical custom with a mechanics based approach to the problem and computational rendering Concrete examples and numerous illustrations complement and clarify the mathematical discussion A supporting Web site offers links to videos of several experiments along with MATLAB code for several of the models This one of a kind book builds a solid understanding of the

theoretical and practical aspects of truly dynamic locomotion in planar bipedal robots Biped Robots Armando Carlos De Pina Filho, 2011-02-04 Biped robots represent a very interesting research subject with several particularities and scope topics such as mechanical design gait simulation patterns generation kinematics dynamics equilibrium stability kinds of control adaptability biomechanics cybernetics and rehabilitation technologies We have diverse problems related to these topics making the study of biped robots a very complex subject and many times the results of researches are not totally satisfactory However with scientific and technological advances based on theoretical and experimental works many researchers have collaborated in the evolution of the biped robots design looking for to develop autonomous systems as well as to help in rehabilitation technologies of human beings Thus this book intends to present some works related to the study of biped robots developed by researchers worldwide **Modeling, Simulation and Optimization of Bipedal Walking** Katja Mombaur, Karsten Berns, 2013-02-28 The model based investigation of motions of anthropomorphic systems is an important interdisciplinary research topic involving specialists from many fields such as Robotics Biomechanics Physiology Orthopedics Psychology Neurosciences Sports Computer Graphics and Applied Mathematics This book presents a study of basic locomotion forms such as walking and running is of particular interest due to the high demand on dynamic coordination actuator efficiency and balance control Mathematical models and numerical simulation and optimization techniques are explained in combination with experimental data which can help to better understand the basic underlying mechanisms of these motions and to improve them Example topics treated in this book are Modeling techniques for anthropomorphic bipedal walking systems Optimized walking motions for different objective functions Identification of objective functions from measurements Simulation and optimization approaches for humanoid robots Biologically inspired control algorithms for bipedal walking Generation and deformation of natural walking in computer graphics Imitation of human motions on humanoids Emotional body language during walking Simulation of biologically inspired actuators for bipedal walking machines Modeling and simulation techniques for the development of prostheses Functional electrical stimulation of walking

Autonomous Systems – Self-Organization, Management, and Control Bernd Mahr, Huanye Sheng, 2008-09-15 The 2008 TUB SJTU joint workshop on Autonomous Systems Self Organization Management and Control was held on October 6 2008 at Shanghai Jiao Tong University Shanghai China The workshop sponsored by Shanghai Jiao Tong University and Technical University of Berlin brought together scientists and researchers from both universities to present and discuss the latest progress on autonomous systems and its applications in diverse areas Autonomous systems are designed to integrate machines computing sensing and software to create intelligent systems capable of interacting with the complexities of the real world Autonomous systems represent the physical embodiment of machine intelligence Topics of interest include but are not limited to theory and modeling for autonomous systems organization of autonomous systems learning and perception complex systems multi agent systems robotics and control applications of autonomous systems *Springer Handbook of*

Robotics Bruno Siciliano, Oussama Khatib, 2016-07-27 The second edition of this handbook provides a state of the art overview on the various aspects in the rapidly developing field of robotics Reaching for the human frontier robotics is vigorously engaged in the growing challenges of new emerging domains Interacting exploring and working with humans the new generation of robots will increasingly touch people and their lives The credible prospect of practical robots among humans is the result of the scientific endeavour of a half a century of robotic developments that established robotics as a modern scientific discipline The ongoing vibrant expansion and strong growth of the field during the last decade has fueled this second edition of the Springer Handbook of Robotics The first edition of the handbook soon became a landmark in robotics publishing and won the American Association of Publishers PROSE Award for Excellence in Physical Sciences Mathematics as well as the organization's Award for Engineering Technology The second edition of the handbook edited by two internationally renowned scientists with the support of an outstanding team of seven part editors and more than 200 authors continues to be an authoritative reference for robotics researchers newcomers to the field and scholars from related disciplines The contents have been restructured to achieve four main objectives the enlargement of foundational topics for robotics the enlightenment of design of various types of robotic systems the extension of the treatment on robots moving in the environment and the enrichment of advanced robotics applications Further to an extensive update fifteen new chapters have been introduced on emerging topics and a new generation of authors have joined the handbook's team A novel addition to the second edition is a comprehensive collection of multimedia references to more than 700 videos which bring valuable insight into the contents The videos can be viewed directly augmented into the text with a smartphone or tablet using a unique and specially designed app Springer Handbook of Robotics Multimedia Extension Portal <http://handbookofrobotics.org>

Engineering Creative Design in Robotics and Mechatronics Habib, Maki K., Davim, J. Paulo, 2013-06-30 While technologies continue to advance in different directions there still holds a constant evolution of interdisciplinary development Robotics and mechatronics is a successful fusion of disciplines into a unified framework that enhances the design of products and manufacturing processes Engineering Creative Design in Robotics and Mechatronics captures the latest research developments in the subject field of robotics and mechatronics and provides relevant theoretical knowledge in this field Providing interdisciplinary development approaches this reference source prepares students scientists and professional engineers with the latest research development to enhance their skills of innovative design capabilities Intelligent Robotics Systems: Inspiring the NEXT Kairuddin Omar, Md. Jan Nordin, Prahlad Vadakkepat, Anton Satria Prabuwono, Siti Norul Huda Sheikh Abdullah, Jacky Baltes, Shamsudin Mohd Amin, Wan Zuha Wan Hassan, Mohammad Faizul Nasrudin, 2013-08-16 This book constitutes the refereed proceedings of the 16th FIRA Robo World Congress FIRA 2013 held in Kuala Lumpur Malaysia in August 2013 The congress consisted of the following three conferences 5th International Conference on Advanced Humanoid Robotics Research ICAHRR 5th International Conference on Education and

Entertainment Robotics ICEER and 4th International Robotics Education Forum IREF The 38 revised full papers presented were carefully reviewed and selected from 112 submissions They cover various topics related to the technical developments and achievements in the field of robotics **Towards Intelligent Engineering and Information Technology** Imre J. Rudas,János Fodor,2009-09-30 Intelligent engineering systems try to replicate fundamental abilities of humans and nature in order to achieve sufficient progress in solving complex problems In an ideal case multi disciplinary applications of different modern engineering fields can result in synergistic effects Information technology and computer modeling are the underlying tools that play a major role at any stages of developing intelligent systems Chapters in the present volume have been written by eminent scientists from different parts of the world dealing with challenging problems for efficient modeling of intelligent systems The reader can find different characteristics and methodologies of computational intelligence with real life applications Various facets of intelligent engineering and information technology are addressed Starting with theoretical issues from pseudo analysis to parametric classes of digital fuzzy conjunctions for hardware implementation of fuzzy systems diverse aspects of control including quantum as well as fuzzy control and hybrid approaches intelligent robotics dealing with mobile and autonomous robots and new trends approaches and results on information technology machines materials and manufacturing and issues of intelligent systems and complex processes are covered

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